



# OPEN

## Compute Project

Satellite Management Controller  
(Auxiliary Management Controller)

Revision 1.0, Version 1.0

### **Base Specification**

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# Table of Contents

<b>Glossary of Terms</b>	<b>3</b>
<b>1. License</b>	<b>4</b>
<b>1.1. OPTION B: Open Web Foundation (OWF) CLA</b>	<b>4</b>
<b>1.2 Acknowledgements</b>	<b>5</b>
1.3 References	5
<b>2. Compliance with OCP Tenets</b>	<b>6</b>
<b>3. Change Log</b>	<b>7</b>
<b>4. Overview</b>	<b>9</b>
4.1 Architectural Example	10
<b>5. Protocols</b>	<b>10</b>
5.1 Physical bindings supported	11
5.2 Protocol layers supported	11
5.2.1 MCTP	11
5.2.2 PLDM	12
5.2.3 Redfish Device Enablement	13
5.3 Device identification	15
<b>5.4 Device Classes</b>	<b>16</b>
<b>6. API surface</b>	<b>16</b>
6.1 Thermal management	16
6.2 Inventory management	18
6.3 Software management	19
6.4 Fan control	20
6.5 Power Management	21
6.6 Security	21

## Glossary of Terms

This section provides definitions for terms used in this document.

**Server.** Machine hardware that contains a Satellite plug-in. Satellite containers are typically Servers but are not required to be so. So we use the more general term Host for a Satellite container.

**Host.** A generalization of a Satellite container that includes Servers (for PCIe Plug-In Satellites) and motherboards (for SoC Satellites). A Host is managed by a logical Host Management Controller (HMC).

**Satellite.** A dependent group of hardware that is managed by a logical Satellite Management Controller (SMC). Satellites typically are smaller than their Host, are terminal points in the management graph, and contain a single power & thermal domain.

**SMC.** Satellite Management Controller provides a management API to Satellite hardware. SMCs may be backed by one or more discrete hardware components. SMC is typically a low-cost ARM microcontroller running a RTOS with no external DRAM, although this is not prescriptive and any CPU architecture and configuration is acceptable.

**Terminal Hardware.** Hardware that is an endpoint in the management graph. In other words, terminal hardware does not itself manage other hardware. Satellites are terminal hardware.

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## 1.2 Acknowledgements

The Contributors of this Specification would like to acknowledge the following companies for their feedback:

Hewlett Packard Enterprise  
Google  
Samsung  
Dell  
Meta

## 1.3 References

- DMTF DSP0218, Platform Level Data Model (PLDM) for Redfish Device Enablement, [https://www.dmtf.org/sites/default/files/standards/documents/DSP0218\\_1.1.2.pdf](https://www.dmtf.org/sites/default/files/standards/documents/DSP0218_1.1.2.pdf)
- DMTF DSP0233, Management Component Transport Protocol (MCTP) I3C Transport Binding Specification, <https://www.dmtf.org/documents/pmci/management-component-transport-protocol-mctp-i3c-transport-binding-specification-100>
- DMTF DSP0236, Management Component Transport Protocol (MCTP) Base Specification, <https://www.dmtf.org/documents/pmci/management-component-transport-protocol-mctp-base-specification-131>
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- DMTF DSP0240, Platform Level Data Model (PLDM) Base Specification,  
[https://www.dmtf.org/sites/default/files/standards/documents/DSP0240\\_1.1.0.pdf](https://www.dmtf.org/sites/default/files/standards/documents/DSP0240_1.1.0.pdf)
- DMTF DSP0241, Platform Level Data Model (PLDM) over MCTP Binding Specification,  
[http://www.dmtf.org/standards/published\\_documents/DSP0241\\_1.0.0.pdf](http://www.dmtf.org/standards/published_documents/DSP0241_1.0.0.pdf)
- DMTF DSP0248, Platform Level Data Model (PLDM) for Platform Monitoring and Control Specification,  
[https://www.dmtf.org/sites/default/files/standards/documents/DSP0248\\_1.2.0.pdf](https://www.dmtf.org/sites/default/files/standards/documents/DSP0248_1.2.0.pdf)
- DMTF DSP0267, Platform Level Data Model (PLDM) for Firmware Update Specification,  
[https://www.dmtf.org/sites/default/files/standards/documents/DSP0267\\_1.1.0.pdf](https://www.dmtf.org/sites/default/files/standards/documents/DSP0267_1.1.0.pdf)
- DMTF DSP0274, Security Protocol and Data Model (SPDM) Specification,  
[https://www.dmtf.org/sites/default/files/standards/documents/DSP0274\\_1.3.0.pdf](https://www.dmtf.org/sites/default/files/standards/documents/DSP0274_1.3.0.pdf)

## 2. Compliance with OCP Tenets

### 2.1. Openness

The SMC V1.0 specification proposes an ecosystem-enabling set of requirements for peripherals to enable management compatibility between open systems. This allows interoperability between various device classes and host systems.

### 2.2. Efficiency

OEMs invest time to create specifications for industry Independent Hardware Vendors (IHVs) which must be implemented in order to support proper management by the host. IHVs invest time working with multiple OEMs to implement those requirements. The goal of the SMC specification is to standardize those various work streams into a single public OCP specification where both OEM and IHV can more effectively promulgate these requirements.

Additionally, multi-vendor customer environments will benefit from the efficiencies achieved through increased device interoperability and the utilization of a common code base for system management.

### 2.3 Impact

The SMC represents a single set of OCP device manageability requirements allowing for IHV ease of development, time to market, and effective use of engineering resources. Device management ASICs could be developed allowing multiple IHVs to leverage a standardized SMC component providing consistent management across device classes.

## 2.4. Scale

Large scale deployments benefit from the standardization of management capability across multiple device classes, server and device vendors which this specification provides.

Redfish, RDE and PLDM DMTF standards for management are utilized allowing for a common set of APIs and management tools regardless of hardware or software environment or size of server deployment.

## 2.5. Sustainability

Between customers' sustainability initiatives and demands to control energy consumption and costs, the ability to report, analyze and actuate server power usage data has become a key initiative.

The creation of a truly interoperable telemetry environment will allow businesses to datacenters, no matter the size, to more effectively meet sustainability targets. SMC thermal and power management capabilities can be utilized to enable this goal of minimizing power requirements and overall energy usage.

## 3. Change Log

Date	Version #	Author	Description
7/5/2022	0.1	Chad Yoshikawa	Filled in Title, Authors, Contributors and sections 1-3
10/1/2022	0.2	Ed Tanous	Major reorganization. Rewrites to many sections
4/27/2023	0.3	Ed Tanous	Removal of old text, formatting cleanups
9/15/2023	1.0	Chad Yoshikawa	Used recent

Open Compute Project • Satellite Management Controller

			Template, document clean-up and resolved outstanding comments.



## 4. Overview

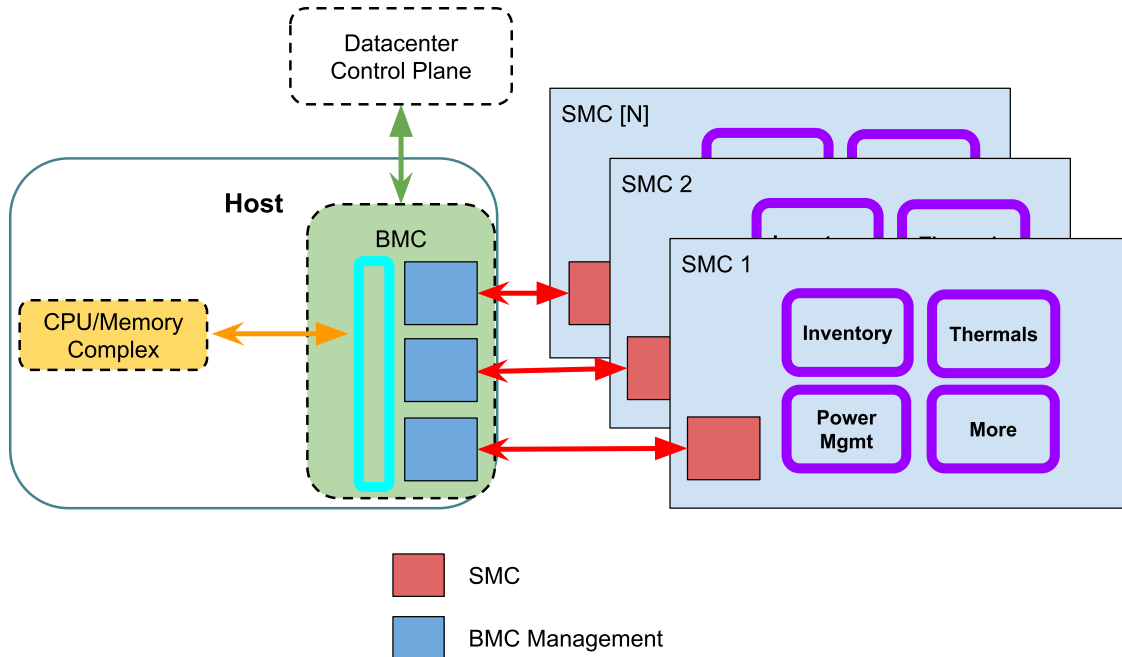
The Satellite Management Controller specification defines a validatable management interface between a satellite container (“server” or more generally a “host”) and simple hardware plug-ins (“satellites”). For example, for a server and PCIe plug-in card, the *host* server manages the *satellite* plug-in.

Satellites are simple: they do not manage other devices and typically contain a single thermal, power and security domain. Note that the satellite and host may not be discrete hardware; host and satellite may be integrated onto the same board in the case of a tray and its SoC.

Satellite conformance can be validated using software tools, which enables independent hardware development and bring-up. To provide validation, the SMC specification defines a compatibility test suite (CTS) to ensure conformance to specified functional requirements.

The management interface additionally specifies SLOs for operations such as firmware update and power management operations. These SLOs may impose constraints on the underlying hardware. For example, timely firmware update may require i3c (vs. i2c) or higher-bandwidth management links.

## 4.1 Architectural Example



SMC includes all API definitions required for managing a peripheral device from an out of band management controller (BMC) in the most common configuration. While other configurations may exist that this specification fulfills, the above diagram is considered the baseline. This specification may reference elements of the baseline configuration as examples. Other configurations may exist.

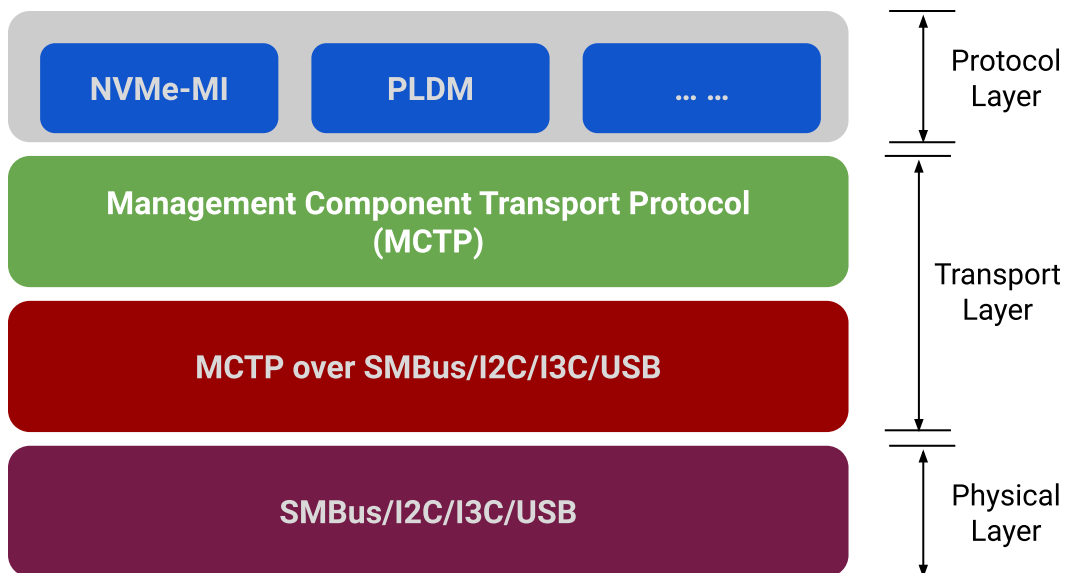
The SMC specification explicitly does not define any physical connectors, physical form factors, or specifications for non SMC components, although other specifications (such as the Modular Hardware Management [DC-SCM](#)) may define connector specifications that *may* be used in deployments. For some examples, this specification may assume a PCIe 16X connector, and a single socket server with BMC.

## 5. Protocols

SMC devices *shall* implement DSP0236 (Management Component Transport Protocol (MCTP) Base Specification).

## 5.1 Physical bindings supported

Devices meeting this specification shall implement DSP0233 ((MCTP) I3C Transport Binding Specification) OR DSP0237 (MCTP) SMBus/I2C Transport Binding Specification OR DSP0238 (MCTP) PCIe VDM Transport Binding Specification. Other physical bindings, such as USB, that have MCTP bindings are allowed. Devices shall implement these protocols without requiring an on-board i2c mux in the protocol path.



## 5.2 Protocol layers supported

### 5.2.1 MCTP

- Compliance with MCTP Base Protocol Specification
  - i. The device will comply to all Endpoint requirements as specified in this section
  - ii. For SMBus (Binding) Protocol, the device shall not be the MCTP Bus Owner
  - iii. "The device shall support receiving an MCTP Set Endpoint ID command at any time (Standby or Main) power is applied. For example, the BMC firmware could be updated resulting in a BMC reset. The BMC initialization sequence will go out and dynamically discover devices and assign Endpoint IDs. While in most cases, the same Endpoint ID will be assigned, this is not guaranteed. The BMC will query the device to see if an Endpoint ID has been previously assigned and is not in conflict with any other assigned Endpoint.

## Open Compute Project • Satellite Management Controller

- Specific compliance with Section “MCTP Message Types”
- Compliance with Section “MCTP Control Protocol”
- Compliance with Section “MCTP Control Messages”
- Support Section “MCTP Control Message Command Codes”, “MCTP Control Command Numbers”
- Support Section “Prepare for Endpoint Discovery”
- Support Section “Endpoint Discovery”

<b>MCTP Control Command (DSP0236)</b>	<b>Implementation</b>
0x01 Set Endpoint ID	Required
0x02 Get Endpoint ID	Required
0x03 Get Endpoint UUID	Required
0x04 Get MCTP Version Support	Required
0x05 Get Message Type Support	Required
0x06=Get Vendor Defined Message Support	Required
0x0B=Prepare for Endpoint Discovery	Required (PCIe VDM)
0x0C=Endpoint Discovery	Required (PCIe VDM)
0x0D=Discovery Notify	Required (PCIe VDM)

### 5.2.2 PLDM

<b>PLDM Messaging Control and Discovery Command Codes (DSP0240)</b>	<b>Implementation</b>
0x01 SetTID	Required

0x02 GetTID	Required
0x03 GetPLDMVersion	Required
0x04 GetPLDMTypes	Required
0x05 GetPLDMCommands	Required
0x06 SelectPLDMVersion	Required
0x07 NegotiateTransferParameters	Required for PLDM FW Multipart
0x08 MultipartSend	Required
0x09 MultipartReceive	Required

### 5.2.3 Redfish Device Enablement

Devices shall implement Redfish Device Enablement DSP0218.

Devices shall support 1 and should support a minimum of 4 concurrent RDE tree operations in parallel.

Devices should be capable of returning the requested portions of the Redfish tree in less than 2 seconds.

RDE Command (DSP0218)		Implementation
0x01 NegotiateRedfishParameters		Required
	DeviceCapabilities	Support atomic resource read to enable consistent reads
	DeviceFeatureSupport	Head and replace optional. Read mandatory. Other features are optional for inventory-only devices and mandatory for full support.

## Open Compute Project • Satellite Management Controller

	DeviceConfigurationSignature	Required as documented
0x02	NegotiateMediumParameters	Required
0x03	GetSchemaDictionary	Required
0x04	GetSchemaURI	Required
0x05	GetResourceETag	Required
0x08	GetRegistryCount	Required for full event support
0x09	GetRegistryDetails	Required for full event support
0x0A	SelectRegistryVersion	Required for full event support
0x0B	GetMessageRegistry	Required for full event support
0x10	RDEOperationInit	Required
OperationType	0=OPERATION_HEAD	Required
	1=OPERATION_READ	Required
	2=OPERATION_CREATE	Conditional - Required for write support
	3=OPERATION_DELETE	Conditional - Required for write support
	4=OPERATION_UPDATE	Conditional - Required for write support
	6=OPERATION_ACTION	Conditional - Required for write support
0x11	SupplyCustomRequestParameters	Required
0x12	RetrieveCustomResponseParameters	Required
0x13	RDEOperationComplete	Required
0x14	RDEOperationStatus	Required
0x16	RDEOperationEnumerate	Required
0x30	RDEMultipartSend	Required for write support
0x31	RDEMultipartReceive	Required

### 5.3 Device identification

For purposes of identification, devices meeting this specification shall expose an interface to a Platform Management FRU Information Storage Definition-compatible API. The SMC API does not specify where this FRU payload must be physically implemented within the card. Implementations may choose to implement in a physical eeprom device, or a virtual eeprom device. Care should be taken in platform design to ensure that the eeprom is available in the required power states consistent with the needs of the baseline server, but this specification does not specify which power states it will be available in. Devices shall implement the following minimum fields.

**Product info area:**

- Manufacturer Name
- Product name
- Product Serial Number

Other fields may be populated at the device's discretion.

## 5.4 Device Classes

The following device classes are supported: Accelerator, NIC, DPU (SmartNIC), Storage Tray, Memory (CXL).

## 6. API surface

The below table calls out for the various device classes, whether a given feature is Required (R) or Conditional (C) on existence of the feature. For example, an Accelerator device may not have a Fan and thus Fan Control is conditional. .

Subsystem	Thermal	Inventory	Software Mgmt	Fan Control	Security	Power Mgmt
<i>Accelerator</i>	R	R	R	C	R	C
<i>NICs</i>	C	R	R	C	R	C
<i>DPUs</i>	R	R	R	C	R	C
<i>Storage Tray</i>	C	R	R	C	R	C
<i>Memory (CXL)</i>	R	R	C	C	R	C

### 6.1 Thermal management

The thermal management subsystem within this specification is intended to allow SMC devices to be managed by a system closed loop thermal system. Devices required to implement the thermal management subsystem shall implement the following Redfish resources and Properties

#### Sensor:

An SMC SensorCollection shall implement one or more sensor resources representing the thermal temperature of the device. The sensor shall have the following properties supported.

- *ReadingUnits*: Shall be present and implemented as “Cel”
- *ReadingType*: Shall be present and implemented as “Temperature”
- Threshold properties of *UpperCritical*, *UpperFatal*, *LowerCritical*, and *LowerFatal*, shall be implemented and represent the design limits of the SMC device in question. Devices with unlimited thermal design limits shall omit these properties.



If an SMC device possess fans, the SMC SensorCollection shall implement a Sensor with the following properties:

- *ReadingUnits*: Shall be present and implemented as “{rev}/min”
- *ReadingType*: Shall be present and implemented as “Rotational”

Devices implementing a single replaceable component *may* implement PLDM type 2 for sensor readings.

### PLDM Type 2 Sensor Requirements

Platform Level Data Model for Platform Monitoring and Control (DSP0248)		Implementation
<i>Terminus Commands</i>		
	0x04 SetEventReceiver	Required for RDE Alert
	0x05 GetEventReceiver	Required for RDE Alert
	0x0B PollForPlatformEventMessage	Required for RDE alert
	0x0C EventMessageSupported	Required
	0x0D EventMessageBufferSize	Required for RDE Alert if MSG size > 256 bytes
<i>Numeric Sensor Commands</i>		Required
	0x11 GetSensorReading	Required
	0x12 GenSensorThreshold	Required
	0x15 GetSensorHysteresis	Required
<i>State Sensor Commands</i>		
	0x21 GetStateSensorReadings	Required
<i>PDR Repository Commands</i>		
	0x50 GetPDRRepositoryInfo	Required
	0x51 GetPDR	Required

	0x53 GetPDRRepositorySignature	Required for RDE
<i>PLDM Event Types</i>		
	0x02 redfishTaskExecutedEvent	Required if implementation cannot complete commands quickly enough to avoid spawning RDE tasks
	0x03 redfishMessageEvent	Required for redfish eventing
	0x04 pldmPDRRepositoryChgEvent	Required for RDE
<i>PDR Type Values</i>		
	2 = Numeric Sensor PDR	Required
	4= State Sensor PDR	Required
	22 = Redfish Resource PDR	Required for RDE

Devices implementing multiple replaceable components shall implement ThermalSubsystem over RDE.

#### **ThermalSubsystem:**

An SMC Redfish ThermalSubsystem shall be implemented, with the following properties:

- *Fans*: With Fan resources representing the fans physically present on this device.
- Fan resources shall contain the following properties
  - *SpeedPercent*

## **6.2 Inventory management**

Requirements within this section are intended to allow inventory management and control of a given device. SMC devices shall implement:

#### **ChassisCollection:**

The ChassisCollection in the device shall contain one or more Chassis Resources representing the device in question. Chassis resources shall implement the following properties:

- *Model*: The value of this property shall match the “Product Name” field present in the FRU identification from section 5.3

- **Manufacturer:** The value of this property shall match the “Manufacturer Name” field present in the FRU identification from section 5.3
- **SerialNumber:** The value of this property shall match the “Serial Number” field present in the FRU identification from section 5.3

SMC devices *may* implement more than one Chassis resource, for representing physical subsystems within the device. Within the SMC chassis collection, there shall be only one Chassis instance (referred to further as the “root”) that does not possess a ContainedBy attribute, and is intended to represent the overall containment of the device. All other devices shall have a ContainedBy Link, traceable to the root device. Root devices shall implement a “Contains” property representing the devices containment

### 6.3 Software management

SMC devices implementing multiple updatable components shall implement an UpdateService. The SMC UpdateService shall implement one or more of FirmwareInventory, or SoftwareInventory collections.

Collections shall contain at least one member of type SoftwareInventory, implementing the following properties

- **Version:** A string representing the software version running on the SMC device.
- **Updateable:** A property that conveys whether or not the device supports update. For SMC devices, this shall be set to True.
- **SoftwareId:** A property to uniquely identify this devices firmware type.
- **AdditionalVersions:** Devices that fit the Redfish descriptions in these properties shall implement AdditionalVersions, with the appropriate subproperties. Devices that do not fit the description shall omit the AdditionalVersions Property.

Devices implementing a single updatable component should implement updates of their firmware through PLDM type 5 (DSP0267 Section 6).

PLDM For Firmware Update DSP0267	Implementation
0x01 QueryDeviceIdentifiers	Required
0x02 GetFirmwareParameters	Required
0x03 QueryDownstreamDevices	Required

0x04 QueryDowstreamIdentifiers	Required
0x05 GetDownstreamFirmwareParameters	Required
0x10 RequestUpdate	Required
0x13 PassComponentTable	Required
0x14 UpdateComponent	Required
0x15 RequestFirmwareData	Required
0x16 TransferComplete	Required
0x17 VerifyComplete	Required
0x18 ApplyComplete	Required
0x1A ActivateFirmware	Required
0x1B GetStatus	Required
0x1C CancelUpdateComponent	Required
0x1D CancelUpdate	Required
0x20 RequestDownstreamDeviceUpdate	Required

SMC devices shall be required to be updated in 1 minute or less, measured in the time that the device is unavailable, and 5 minutes or less from the time the update is requested, including all data transfers to the device.

## 6.4 Fan control

SMC devices containing fans shall implement control and monitoring of those fans through the RDE interface. Devices shall support the Redfish Control schema for fan control within a system. SMC devices *may* run internal control loops in addition to the control loops presented on the RDE interface.

## 6.5 Power Management

If an SMC device supports reset, the Redfish Chassis.Reset action shall be supported.

If an SMC device captures power metrics, the SMC EnvironmentMetric and Sensor collection shall implement the following properties where supported:

- EnergykWh or EnergyJoules
- PowerWatts
- PowerLimitWatts
- ResetMetrics
- AverageReading
- AveragingInterval

## 6.6 Security

Sync with the OCP Security Group around these requirements is required.

Security Protocol & Data Model (SPDM) Specification DSP0274 -  
<https://www.dmtf.org/dsp/DSP0274>

SPDM Request Codes (DSP0274)		Implementation
0x81 GET_DIGESTS		Required
0x82 GET_CERTIFICATE		Required
0x83 CHALLENGE		Required
0x84 GET_VERSION		Required
0xE0 GET_MEASUREMENTS		Required
	MEAS_CAP=10b	Required
	DMTFSpecMeasurementValueType <ul style="list-style-type: none"> <li>• [00h] Immutable ROM</li> <li>• [01h] Mutable FW</li> </ul>	Required
0xE1 GET_CAPABILITIES		Required
	CERT_CAP	Required

	CHAL_CAP	Required
	MEAS_CAP	Required
0xE3 NEGOTIATE_ALGORITHMS		Required
	BaseAsymAlgo [Bit 2] TPM_ALG_RSASSA_3072 [CMA, CNSA, OCP] (Allowed) [Bit 4] TPM_ALG_ECDSA_ECC_NIST_P256 [CMA] (Allowed) [Bit 7] TPM_ALG_ECDSA_ECC_NIST_P384 [CMA, CNSA, OCP] (Preferred)	
	BaseHashAlgo [Bit 0] TPM_ALG_SHA_256 [CMA] (Allowed) [Bit 1] TPM_ALG_SHA_384 [CMA, CNSA, OCP] (Preferred)	
	MeasurementHashAlgo [Bit 1] TPM_ALG_SHA_256 [CMA] (Allowed) [Bit 2] TPM_ALG_SHA_384 [CMA, CNSA, OCP] (Preferred)	
0xFF RESPOND_IF_READY		Required

## Security Requirements

SPDM 1.1 or later is required. The following attributes shall be supported:

- Authentication
- Identification
- Attestation